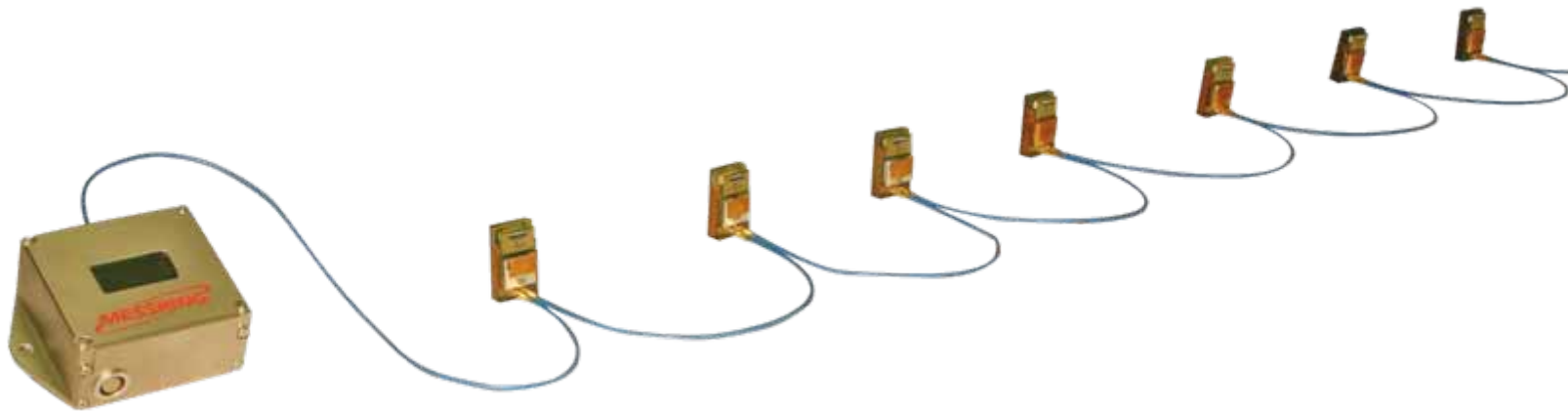


The **M=BUS** Concept



The next generation of shock proof data acquisition

presented file on February 20th 2008 meeting at





- 1. M=BUS[®] Concept**
- 2. Efficiency**
- 3. Integration**
- 4. Calibration**
- 5. Summary**

1. **M=BUS** Concept

■ Current situation in crash testing

- Strict standards and increasing requirements to the car safety
- Higher density of measuring locations in crash tests
- Need of more accurate measurements
- Reduction of transducer sizes
- Restrictions by connector sizes
- Higher effort of data management
- Complex wiring and analogue front end
- Complex database to manage sensor parameters



On-Board data acquisition



Load cell wall

... the **M=BUS** data acquisition fulfils the new demands...

M=BUS simplifies the wiring!

Adaptor Plugs with soldering tags for the analogue sensor wires and necessary bridge completions.



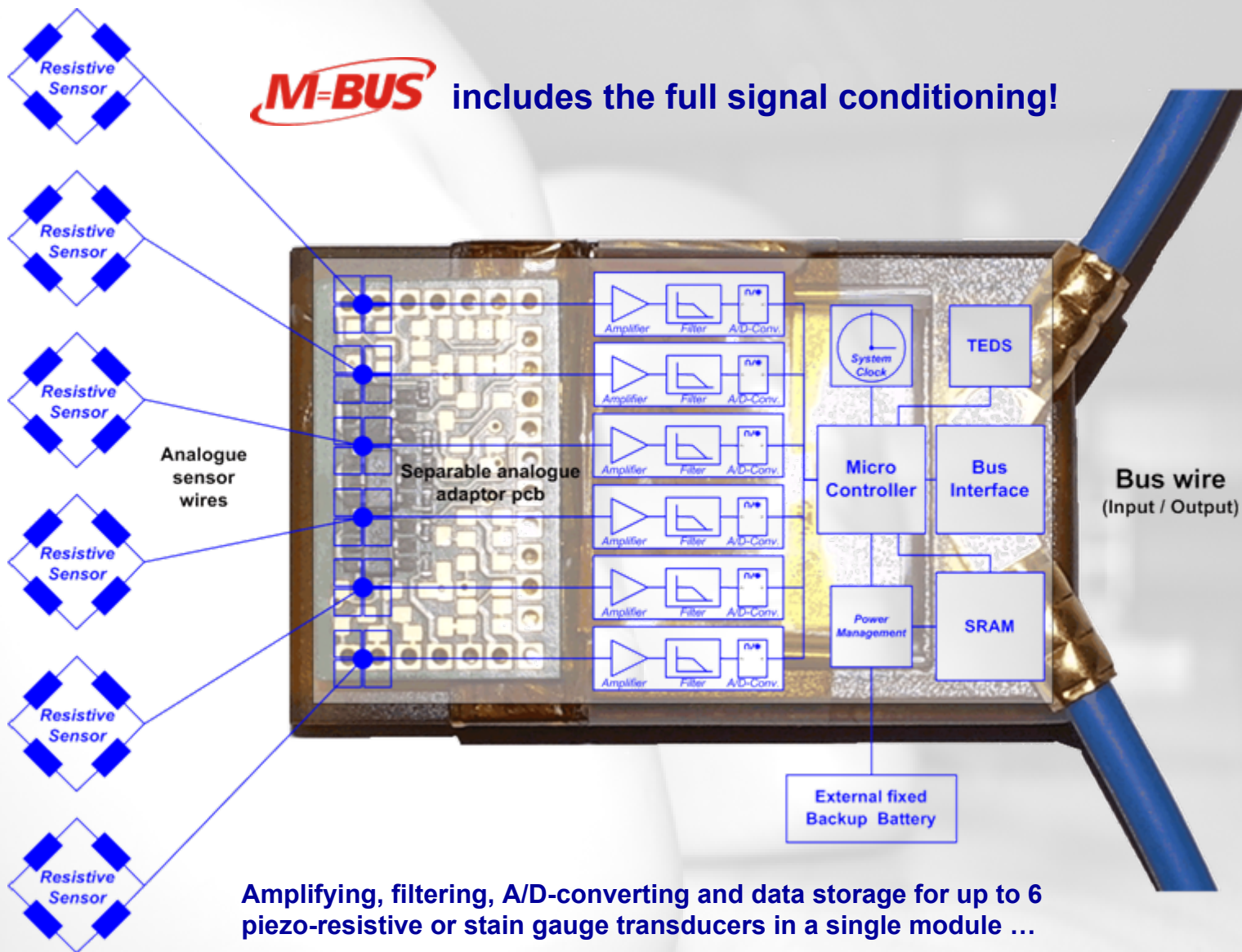
Shrinking length of analogue sensor cables due to locating the M=BUS[®] units near or in the transducers.



Daisy-Chain wiring of up to 32 participants with support of 6 channels each in one M=BUS[®] strand with high flexible 2.5mm diameter coax cables.



M-BUS includes the full signal conditioning!



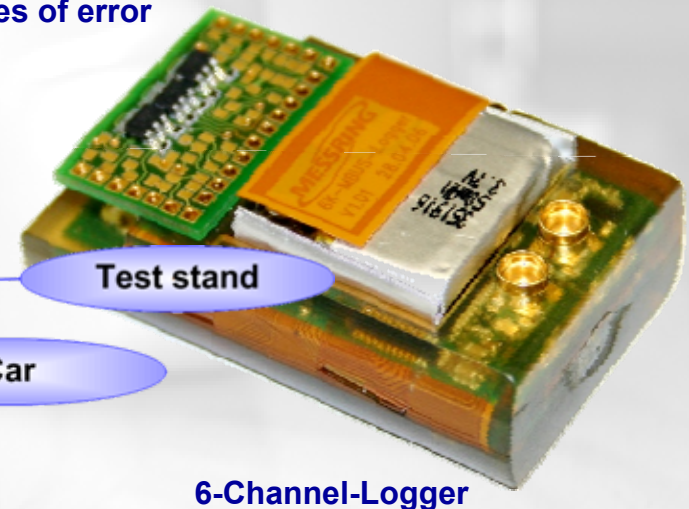
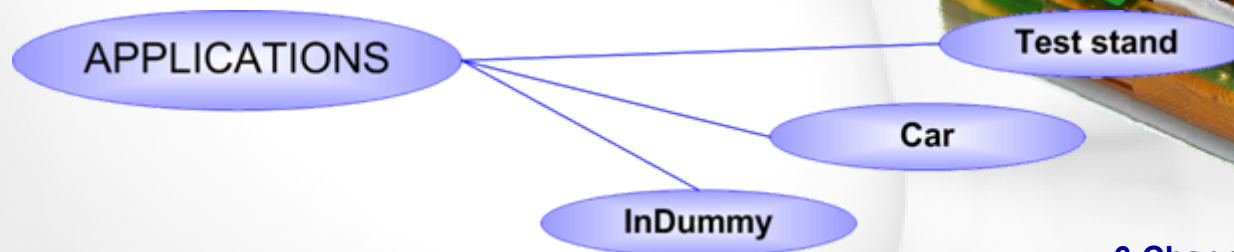
Amplifying, filtering, A/D-converting and data storage for up to 6 piezo-resistive or stain gauge transducers in a single module ...



is the miniaturized data acquisition system based on the MESSRING-BUS-Technology which enables power supply and communication via a single 2.5mm coax cable.

Benefit shortlist:

- Enormous miniaturisation of electronics
- Support of a sufficient amount of measuring channels for all applications
- System decentralisation (better heat and mass distribution)
- Simplification of wiring
- Minimization of disturbances by wiring and sources of error
- Prevention of failure and operating errors
- Well designed for a wide range of applications





**Hot Mold Logger 3C / 6C
(3 or 6 channels)**



M-BUS[®] Ethernet Gateway



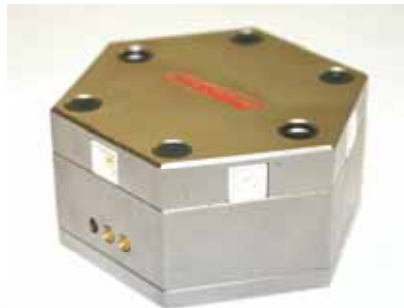
M-BUS[®] Terminator



M=BUS® USB Gateway



M=BUS® NA33 Gateway



M=BUS® Status display



M=BUS® Interface Triax Accelerometer

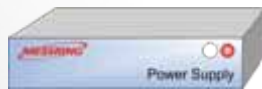
M-BUS as a compact system!



Crash Analysis PC



Trigger Source



Power Supply



Battery Pack

or



Sensors in cars



Sensors in dummies



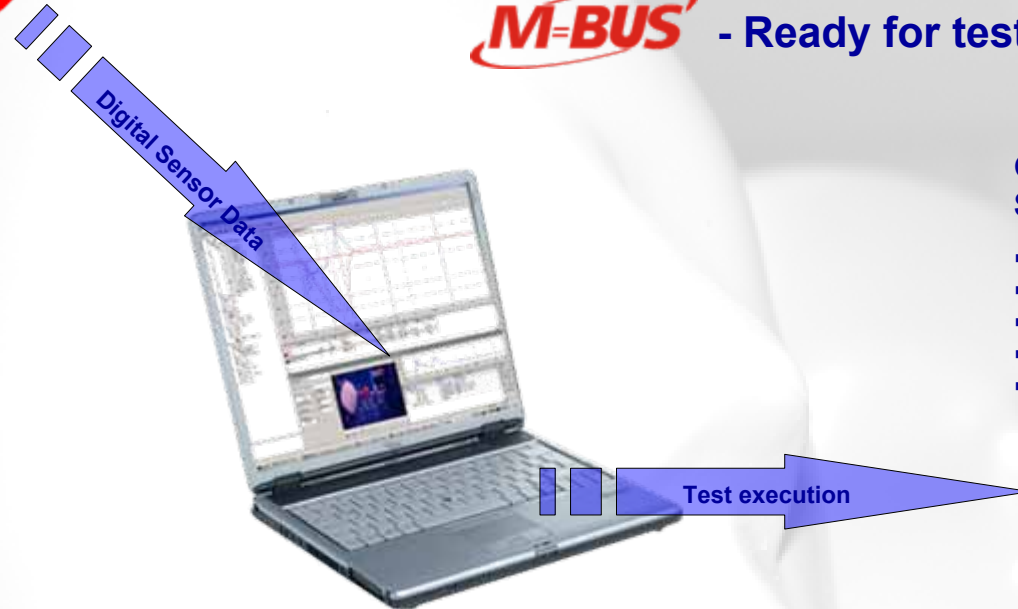
Sensors in test stands



Sensors on sled

Direct connection to PC with support of up to 1152 channels.

M=BUS - Ready for test!



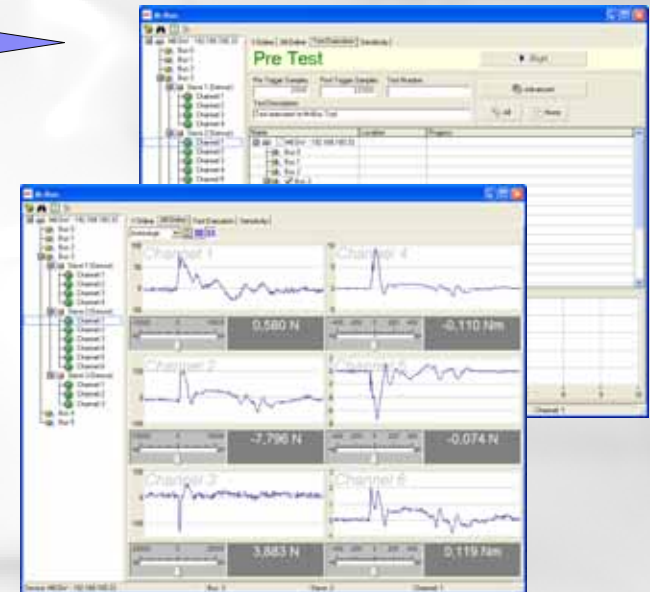
Get started with the supplied M=BUS® Software Tool for the test execution:

- Sensor Check
- Online View
- TEDS Editor
- Test Preparation and Execution
- Data providing in ISO-files

Complete data analysis with the additional CrashSoft3® Package...



...and full compatibility to other data analysis software products.



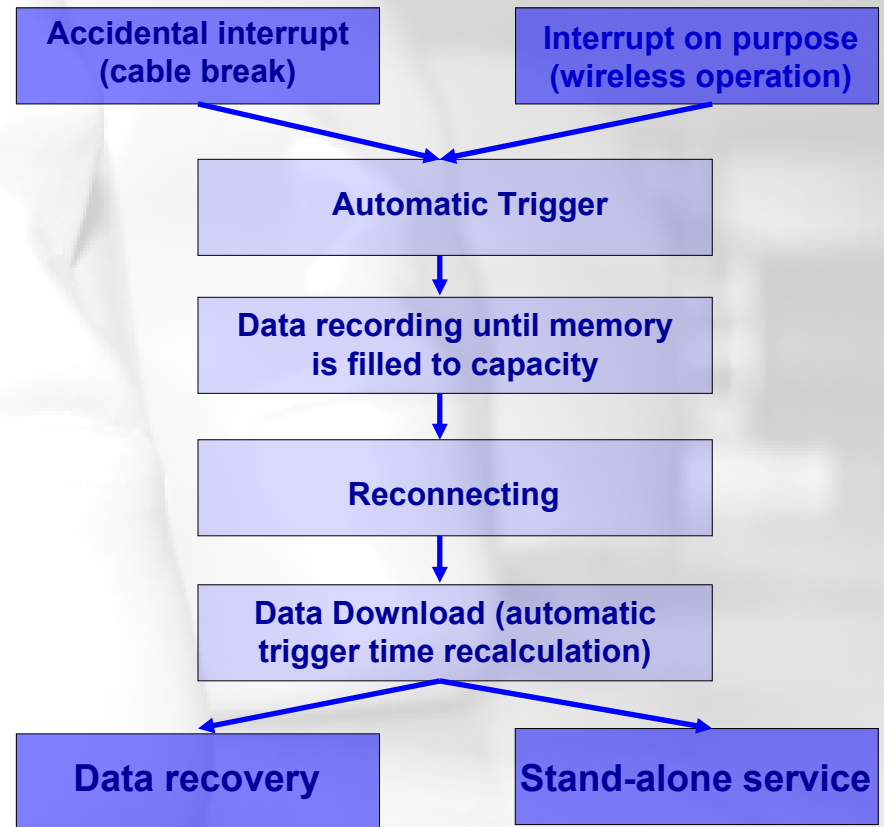
M=BUS acquires the data autonomically!



External fixed Backup Battery with status monitoring by software.

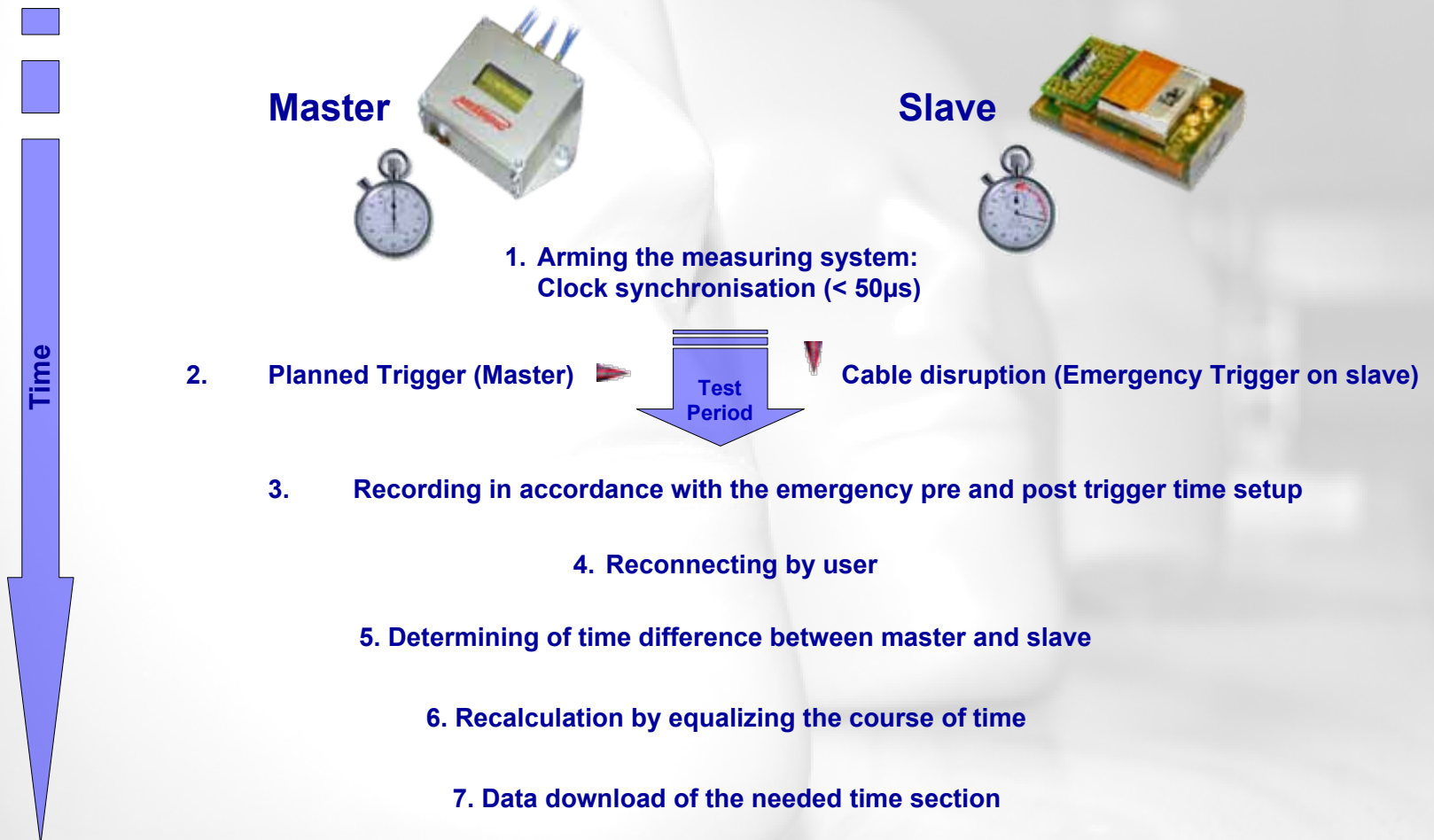


A integrated Backup System saves the data after cable disruption.



M=BUS synchronizes data and time!

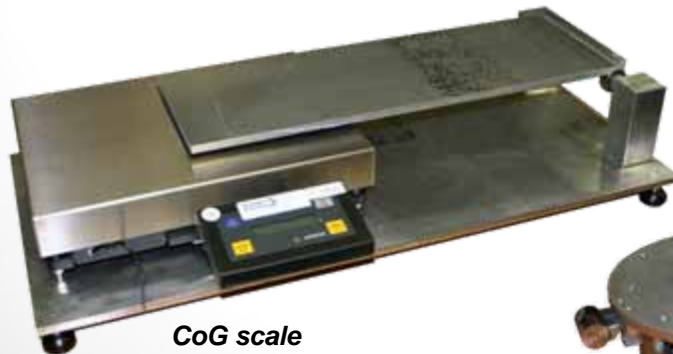
Recalculation of the trigger time (t_0) realized by synchronized clocks in master and slaves:



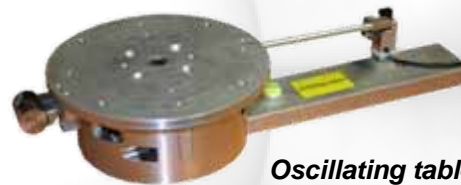
M-BUS meets the requirements!

Proved compliance to SAE, ECE/EG,
CFR, ISO and MISRA standards:

- Conformable Engineering
- Shock tests
- Sled tests
- Climate chamber tests
- Electronics check
- Electrostatic discharge test
- Mass property check
- Durability tests
- Software reliability research



CoG scale



Oscillating table



HydroBrake sled test facility



Drop tower

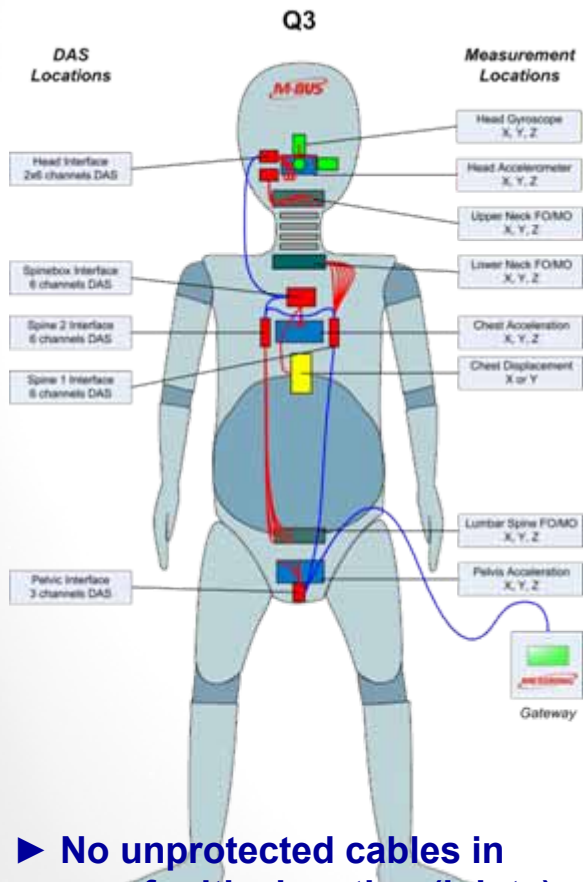


Climate chamber

2. **M=BUS** Efficiency

M=BUS - Technology ahead!

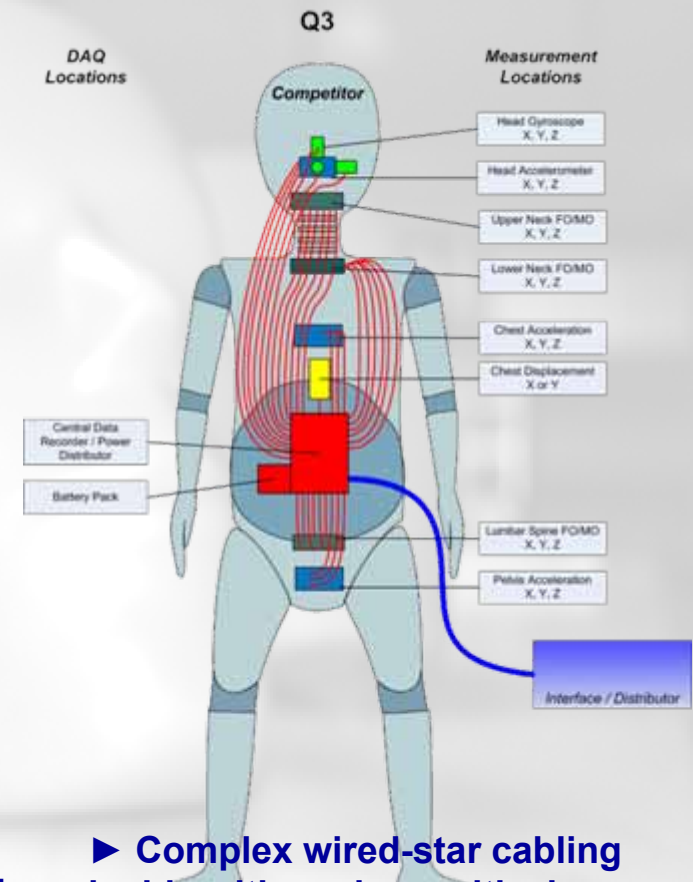
Decentralized M=BUS®



► No unprotected cables in areas of critical motion (joints)

■ Protected cables
■ Unprotected cables

Centralized systems



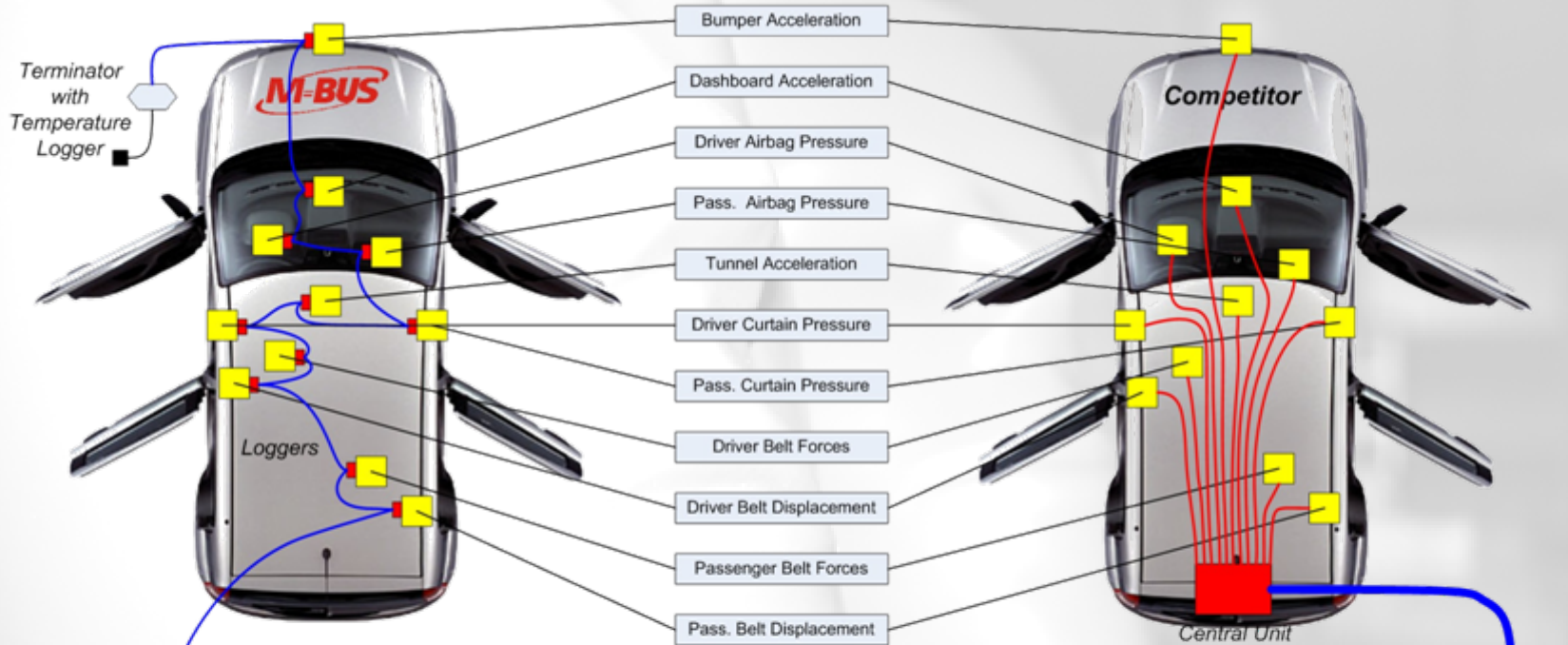
► Complex wired-star cabling inside with neck as critical area

M=BUS - Technology ahead!

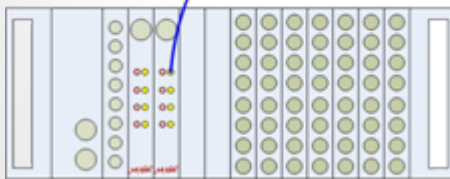
M=BUS®

Centralized systems

Measurement Locations (examples)



Protected cables
Unprotected cables

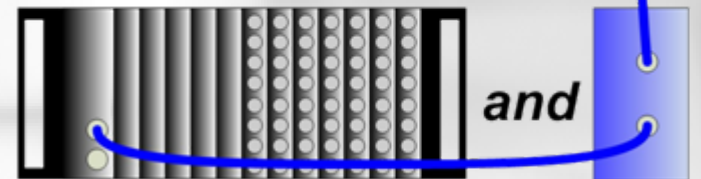


NA33 with M=BUS® boards
(simultaneous analogue board usage)

or



Gateway



Data Acquisition Device

Gateway/
Distributor

3. **M=BUS** Integration

M=BUS - The Closer Look:

Hybrid III Family



ES2



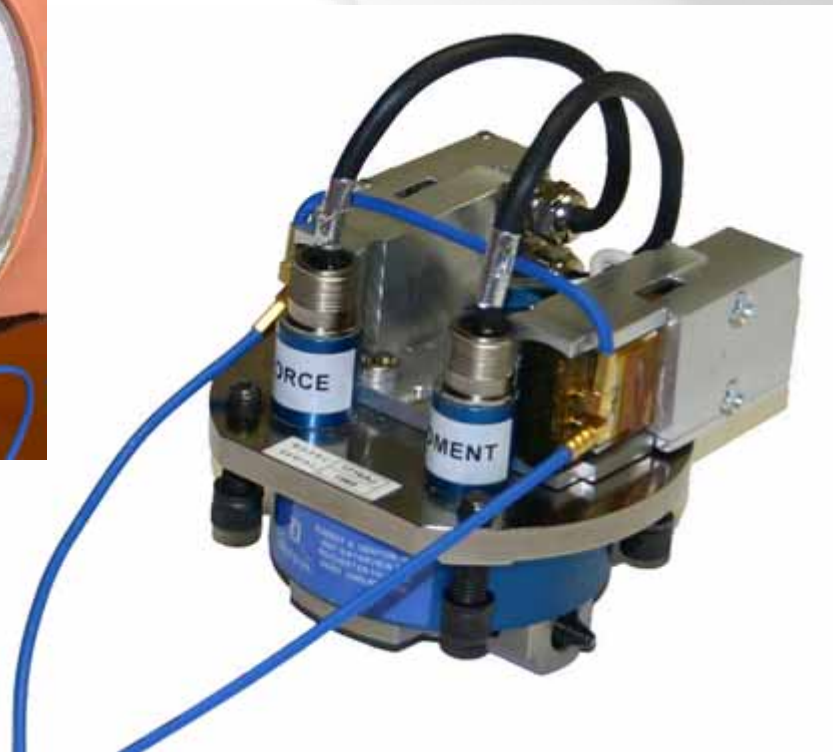
Q-series



Adaptation:

- Standard dummy parts
- No modifications
- Balanced component masses
- Balanced centers of gravity
- Adapted Moments of Inertia
- Protected Wires (cable routing inside the structures, joints bridged by M=BUS®)

M=BUS Head Interface



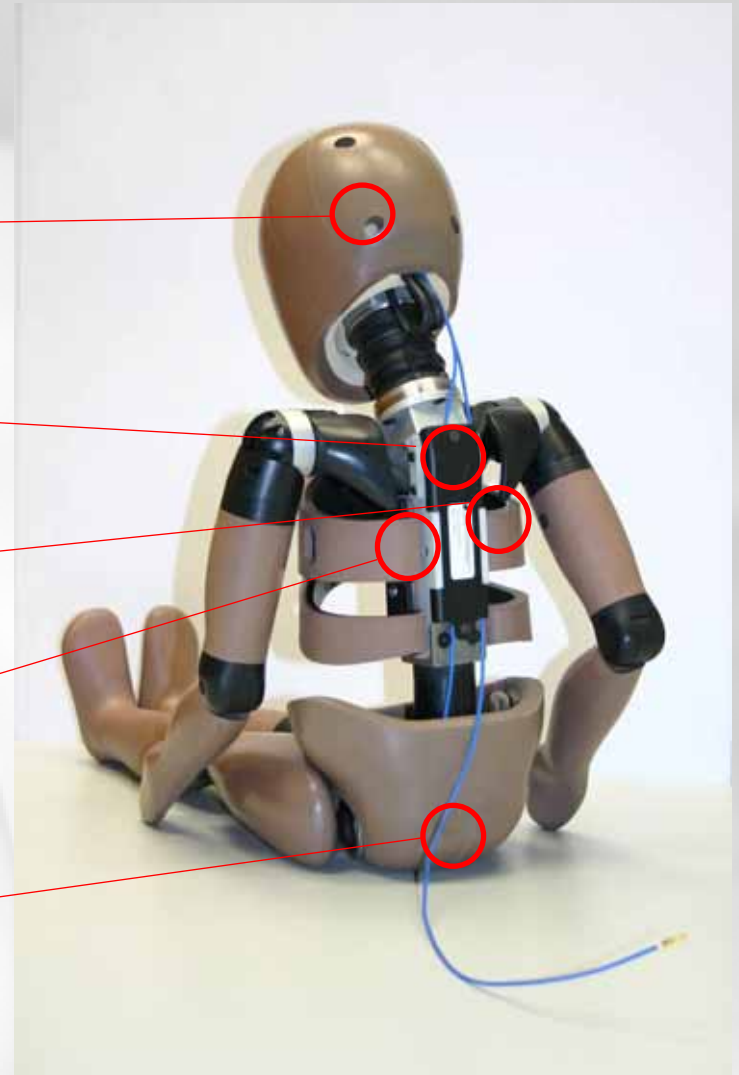
??HEAD000HFACX?
??HEAD000HFACY?
??HEAD000HFACZ?
??NECKUP00HFFOX?
??NECKUP00HFFOY?
??NECKUP00HFFOZ?
??NECKUP00HFMOX?
??NECKUP00HFMOY?
??NECKUP00HFMOZ?

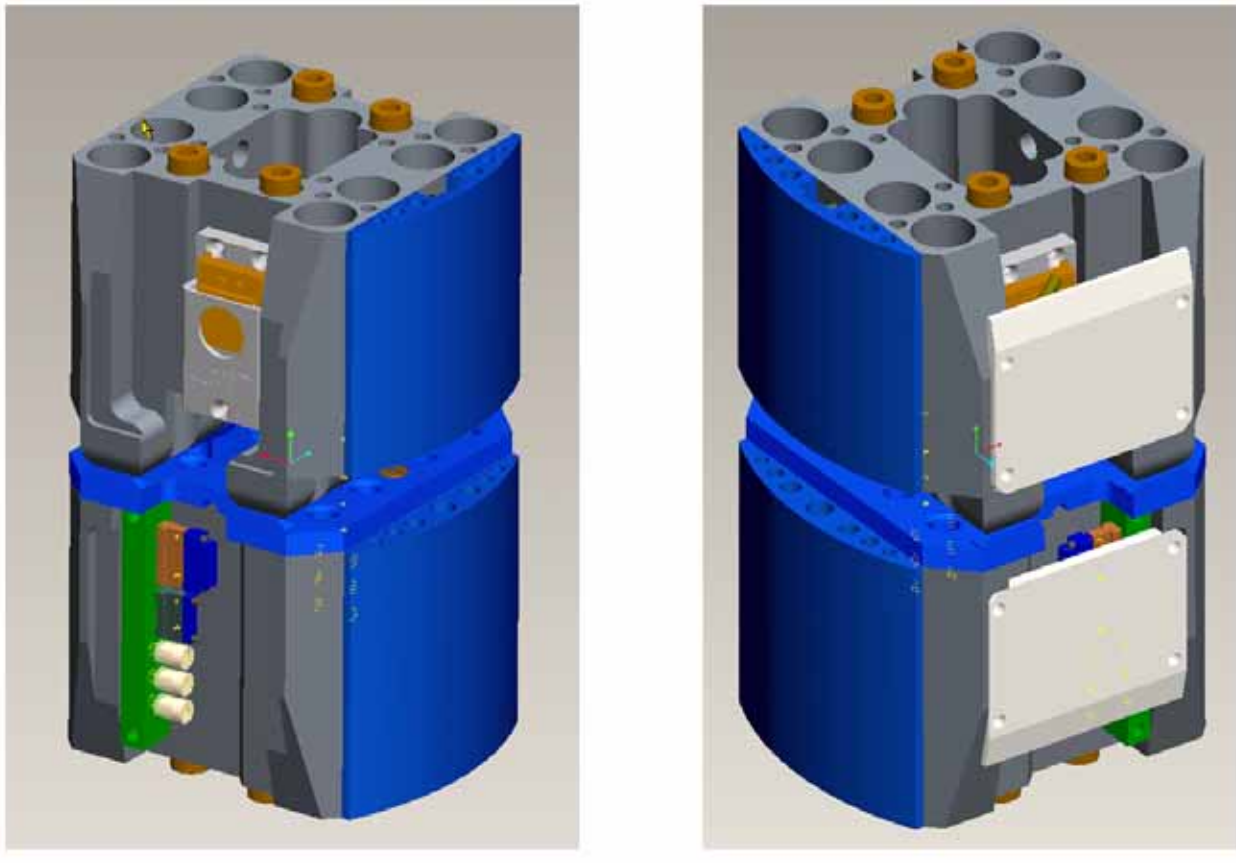
Extensible to:

??HEAD000HFAVX?
??HEAD000HFAVY?
??HEAD000HFAVZ?

M=BUS - Interfaces:

1. **Head Interface Q3**
2. **Spinebox Interface Q3**
3. **Spine 1 Interface Q3**
4. **Spine 2 Interface Q3**
5. **Pelvic Interface Q3**



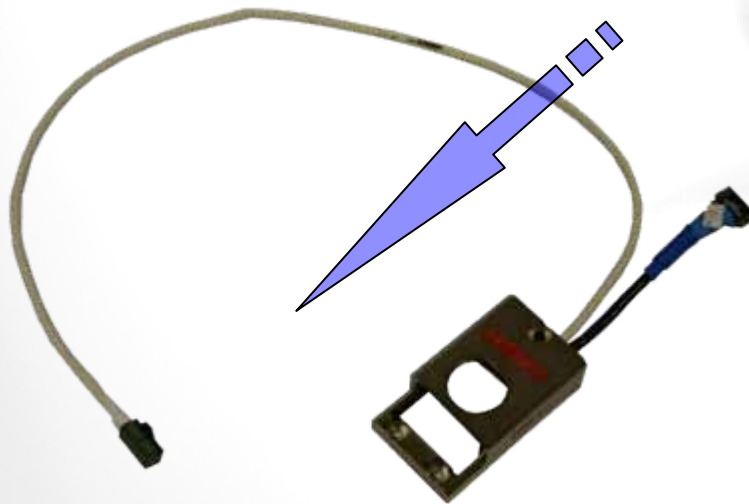
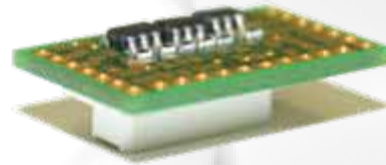
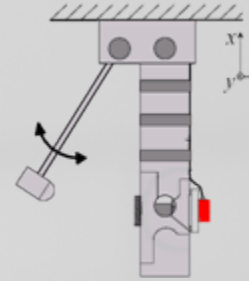


- 2 M=BUS Logger with 12 channels
- Wireless operation with M=BUS tear off connector

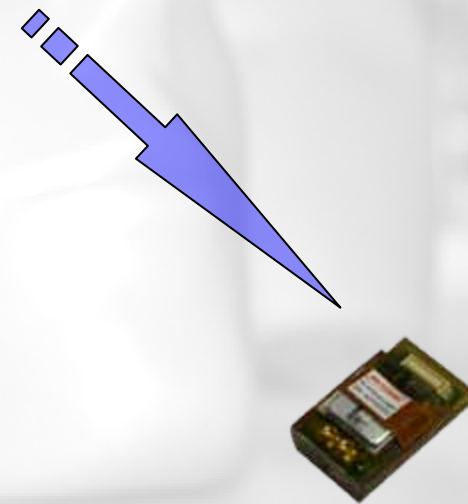
4. **M=BUS** Calibration

Separate Calibration of Sensor and Data Acquisition

Separation of Sensor and
Logger with adapter PCB

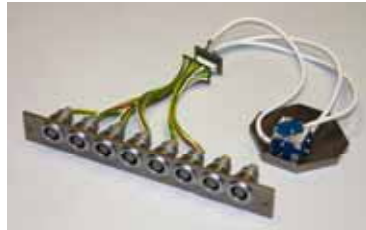


Analogue Sensor Calibration



Voltage Calibration

Analogue Sensor Calibration

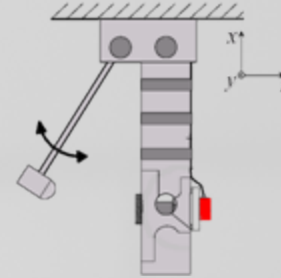


Connection of Sensor with LEMO-Adapter to conventional Calibration System

Voltage Calibration of Data Acquisition



Connection of Logger with LEMO-Adapter to conventional Calibration System

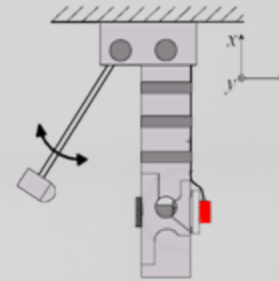


Manual Input of Calibration Data into electronic data sheet (TEDS)

Report Sensor Calibration

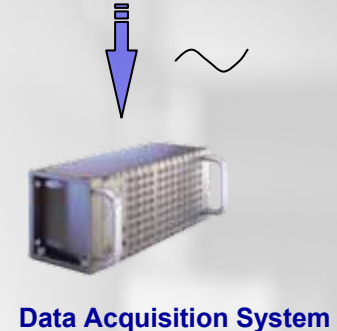
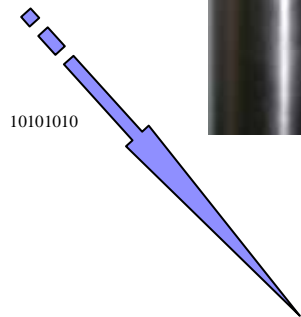
Report DAS-Calibration

Common Calibration of Sensor and Data Acquisition

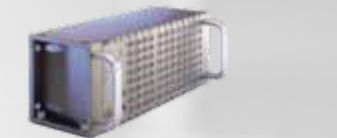


M=BUS[®]-Sensor-Module

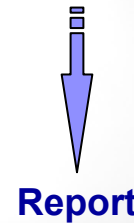
Analog Reference Sensor



Sensor Calibration Software

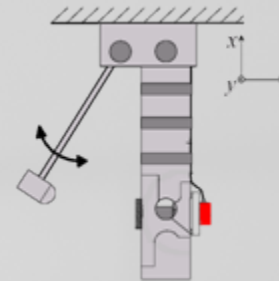


Data Acquisition System



Report

Software for M=BUS[®]-Calibration



M-Bus Tool

Slave | Channel | Amplifier Cal | Sensitivity | 1 Online | All Online | Simple Cal | Pendulum Cal | Download | Gateway | Test Execution

MBUS HD

- Bus 0
 - Slave 1 (Sensor)
 - HEAD000...
 - HEAD000...
 - HEAD000...
 - Bus 1
 - Bus 2
 - Bus 3

Analyse Results

Parameter	Reference	M=Bus	M=Bus (Phys)
Offset	-0,272 g	32781	-0,217 g
Peak	-110,335 g	39910	-111,213 g
Peak - Offset	-110,064 g	7129	-110,996 g
Time of peak	1,65 ms	1,65 ms	1,65 ms

Use:

- Linear Approximation
- Peak and Offset

Save to sensor

Save curves

Source of values	ADC Offset	ADC Max	Range	Slope
Current values	FFFF	828D	500 g	-1,5570e-
Linear approximation	FFFA	82C4	500 g	-1,5598e-
Peak and Offset	FFFB	817A	500 g	-1,5439e-

Sensor to calibrate

Device	Bus	Slave	Channel
MBUS-HD	0	1	2

Location code	Direction	Dimension
HEAD000H3	+Y	acceleration

Back | Next

Device: MBUS-HD | Bus: 0 | Slave: 1 | Channel: 2 | Error

5. **M=BUS** Summary

M=BUS simplifies work!

- **More freedom in wiring (Daisy-Chain)**
- **Quicker maintenance and test preparation (One-wire-bus connectors)**
- **Easier dummy equipping and full reversibility (no structure modification)**
- **Less faults (user oriented development)**
- **More security (backup system)**
- **More flexibility (spectrum of applications)**
- **Fast simultaneous download**
- **Less effort in data management (TEDS and software organisation)**
- **Analogue as well as digital sensor calibration**
- **Less costs per channel (efficient concept)**

???

**Thanks for your
attention!!!**

